Three stories on deep linear networks

SIGMA 2024 Workshop, CIRM, Marseille October 29th, 2024

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Deep linear networks for regression are implicitly regularized towards flat minima NeurIPS 2024



Maximal learning rate for gradient descent

Gradient flow from a small-scale initialization

Gradient flow from a residual initialization

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> Optimization problem

 $\min_{\mathcal{W}\in\mathbb{R}^p} R^L(\mathcal{W})\,.$

Gradient descent (GD):

$$\mathcal{W}_{t+1} = \mathcal{W}_t - \eta \nabla R^L(\mathcal{W}_t)$$
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> Maximal admissible value of η ?

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- > Maximal admissible value of η ?
- **Notation:** the sharpness S(W) is the largest eigenvalue of the Hessian of R^L .
- **Convex optimization:** descent lemma for gradient descent (GD) with learning rate η if

$$\eta < rac{2}{\sup_{\mathcal{W}\in\mathbb{R}^p}S(\mathcal{W})} \quad \Leftrightarrow \quad \sup_{\mathcal{W}\in\mathbb{R}^p}S(\mathcal{W}) < rac{2}{\eta}\,.$$

> This is a necessary condition for convergence for a quadratic objective.





see Wu, Bartlett, Telgarsky, Yu (2024).

Deep linear networks for regression

> Deep linear networks

$$x \mapsto p^\top W_L \dots W_1 x$$
,

with $x \in \mathbb{R}^d$, parameters $\mathcal{W} = \{ W_k \in \mathbb{R}^{d_k \times d_{k-1}} \}_{1 \le k \le L}$, and $p \in \mathbb{R}^{d_L}$ is a fixed vector.

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2 key settings

- ▷ Multi-layer perceptron: $d_L = 1$ and p = 1.
- ▷ Residual network: $d_0 = \cdots = d_L = d$, $W_k \approx I$.

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- ▷ Multi-layer perceptron: $d_L = 1$ and p = 1.
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> Regression task: $X \in \mathbb{R}^{n \times d}$, $y \in \mathbb{R}^n$, π^* optimal regressor of minimal norm.

> Mean squared error:

$$R^{L}(\mathcal{W}) = \frac{1}{n} \|y - XW_{1}^{\top} \dots W_{L}^{\top}p\|_{2}^{2}.$$

GD fails when η exceeds a critical value





Where does the critical learning rate value come from?

Damian, Nichani, Lee (2023)

GD implicitly solves

$$\min_{\mathcal{W}} R^L(\mathcal{W})$$
 such that $S(\mathcal{W}) \leq rac{2}{\eta}$.

> Interpretation: GD cannot converge to a minimizer as soon as

$$\inf_{\mathcal{W}\in \arg\min(R^L)} S(\mathcal{W}) > \frac{2}{\eta} \quad \Leftrightarrow \quad \eta > \frac{2}{\inf_{\mathcal{W}\in \arg\min(R^L)} S(\mathcal{W})} \,.$$

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Theorem (Mulayoff and Michaeli, 2020; M. and Chizat, 2024)

$$\inf_{\mathcal{W}\in\arg\min(R^L)} S(\mathcal{W}) \sim 2La \|\pi^\star\|_2^2 \quad \text{with} \quad a = \left(\frac{\pi^\star}{\|\pi^\star\|}\right)^\top \frac{X^\top X}{n} \frac{\pi^\star}{\|\pi^\star\|} \,.$$

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> GD fails if η > 1/(La||π^{*}||²/₂).
 > After training to a minimizer, 2La||π^{*}||²/₂ ≤ S(W) ≤ 2/η.

Solution GD fails if
$$\eta > \frac{1}{La \|\pi^{\star}\|_{2}^{2}}$$
.



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0.200 --- depth: 5 و ____ ف ف د _____ -x- depth: 10 0.175 0.150 0.150 --- depth: 20 -+- depth: 40 mal 0.125 0.125 0.100 8 distan 0.075 8 0.050 under 0.025 0.000 10⁻² 10^{-1} Learning rate

After training, $2La \|\pi^{\star}\|_2^2 \leq S(\mathcal{W}) \leq \frac{2}{\eta}$.



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From a small-scale initialization

- > Sharpness does not saturate at $2/\eta$.
- ▷ The final sharpness is independent of the learning rate.

Maximal learning rate for gradient descent

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Our setting

> Deep linear networks

 $x \mapsto W_L \dots W_1 x$,

with $x \in \mathbb{R}^d$, parameters $\mathcal{W} = \{ W_k \in \mathbb{R}^{d_k \times d_{k-1}} \}_{1 \le k \le L}$, and $d_L = 1$. Mean squared error:

$$R^{L}(\mathcal{W}) = \frac{1}{n} \|y - XW_{1}^{\top} \dots W_{L}^{\top}\|_{2}^{2}.$$

Gradient flow (GF):

$$\frac{dW_k}{dt}(t) = -\frac{\partial R^L}{\partial W_k}(t) \,.$$

▶ Initialization such that $R^{L}(\mathcal{W}(0)) \leq \frac{1}{n} \|y\|_{2}^{2}$ and $\nabla R^{L}(\mathcal{W}(0)) \neq 0$.

2 questions

- Convergence of gradient flow?
- Structure of the minimizer?

Initialization scale controls the structure of the weights

Define σ_k, u_k, v_k the first singular value, left vector and right vector of W_k , and

$$\varepsilon := 3 \max_{1 \le k \le L} \| W_k(0) \|_F^2 + 2 \sum_{k=1}^{L-1} \| W_k(0) W_k^\top(0) - W_{k+1}^\top(0) W_{k+1}(0) \|_2.$$

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Lemma

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Lemma

The parameters following gradient flow satisfy for any $t \geq 0$ that

Proof: for any time $t \ge 0$ and any $k \in \{1, \dots, L-1\}$,

$$W_{k+1}^{\top}(t) W_{k+1}(t) - W_{k+1}^{\top}(0) W_{k+1}(0) = W_k(t) W_k^{\top}(t) - W_k(0) W_k^{\top}(0)$$

+ computations...

Convergence of GF

Theorem (M. and Chizat, 2024)

The network satisfies the Polyak-Łojasiewicz condition for $t \ge 1$, in the sense that there exists some $\mu > 0$ such that, for $t \ge 1$,

$$\sum_{k=1}^{L} \left\| \frac{\partial R^{L}}{\partial W_{k}}(t) \right\|_{F}^{2} \ge \mu(R^{L}(\mathcal{W}(t)) - R_{\min}).$$

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Beginning of the proof:

$$\frac{\partial R^L}{\partial W_1}(t) = \underbrace{\left(W_L(t)\dots W_2(t)\right)^\top}_{d_1 \times 1} \underbrace{g^\top}_{1 \times d_0}.$$

Therefore

$$\left\| \frac{\partial R^{L}}{\partial W_{1}}(t) \right\|_{F}^{2} = \| W_{L}(t) \dots W_{2}(t) \|_{2}^{2} \| g \|_{2}^{2}$$

$$\geq 4\lambda \| W_{L}(t) \dots W_{2}(t) \|_{2}^{2} (R^{L}(\mathcal{W}(t)) - R_{\min}) .$$

Corollary

Assume that $32L\sqrt{\varepsilon} \leq 1$ and that the data covariance matrix $\frac{1}{n}X^{\top}X$ is full rank with smallest (resp. largest) eigenvalue λ (resp. Λ).

Then the gradient flow dynamics converge to a global minimizer \mathcal{W}^{SI} of the risk, such that

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For
$$k \in \{1, \ldots, L\}$$
, $\|W_k^{SI}\|_F^2 - \|W_k^{SI}\|_2^2 \le \varepsilon$, (rank-one)
for $k \in \{1, \ldots, L\}$, $\left(\frac{\|\pi^*\|_2}{2}\right)^{1/L} \le \sigma_k^{SI} \le \left(2\|\pi^*\|_2\right)^{1/L}$, (low-norm)
for $k \in \{1, \ldots, L-1\}$, $\langle v_{k+1}^{SI}, u_k^{SI} \rangle^2 \ge 1 - \frac{\varepsilon}{\left(2\|\pi^*\|_2\right)^{2/L}}$, (alignment)
 $1 \le \frac{S(W^{SI})}{S_{\min}} \le 4\frac{\Lambda}{\lambda}$. (low-sharpness)

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From multi-layer perceptrons to residual networks

 $h_{k+1} = f(h_k, V_{k+1})$ $h_{k+1} = \frac{h_k}{h_k} + f(h_k, V_{k+1})$ 60 60 50 50 (%) 40 (%) 40 34-laver 30 18-layer plain-18 ResNet-18 min plain-34 ResNet-34 34-layer 20 20 30 40 50 20 10 10 30 40 50 iter. (1e4) iter. (1e4)

He, Zhang, Ren, Sun (2015)

$$h_{k+1} = h_k + V_{k+1}h_k = \underbrace{(I + V_{k+1})}_{=:W_{k+1}}h_k$$

Solution V_{k+1} initialized at V(0) is equivalent to GF on W_{k+1} initialized at I + V(0).

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with $x \in \mathbb{R}^d$, parameters $\mathcal{W} = \{ W_k \in \mathbb{R}^{d \times d} \}_{1 \le k \le L}$, and $p \in \mathbb{R}^d$ is fixed.

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> Initialization:

$$W_k(0) = I + \frac{s}{\sqrt{Ld}} N_k \,.$$

Zoom on the initialization

$$W_k(0) = I + rac{s}{\sqrt{Ld}} N_k$$
.

- $> N_k$: matrices with independent standard Gaussian entries.
- $1/\sqrt{d}$ factor: "right" scaling in the large-width limit.
- > $1/\sqrt{L}$ factor: "right" scaling in the large-depth limit.
- s factor: hyperparameter (independent of width and depth).
- On scaling factors, see (for example) Glorot and Bengio (2010); He, Zhang, Ren, Sun (2015); Arpit, Campos, Bengio (2019); Marion, Fermanian, Biau, Vert (2022); Chizat and Netrapalli (2023); Yang, Yu, Zhu, Hayou (2024).

Convergence of GF

Theorem (M. and Chizat, 2024)

There exist $C_1, \ldots, C_5 > 0$ depending only on s such that, if $L \ge C_1$ and $d \ge C_2$, then, with probability at least

$$1-16\exp(-C_3 d)\,,$$

if

$$R^L(\mathcal{W}(0)) - R_{\min} \le \frac{C_4 \lambda^2 \|p\|_2^2}{\Lambda},$$

the gradient flow converges to a global minimizer \mathcal{W}^{RI} of the risk. Furthermore, the minimizer \mathcal{W}^{RI} satisfies

$$W_k^{\mathsf{RI}} = I + \frac{s}{\sqrt{Ld}} N_k + \frac{1}{L} \theta_k^{\mathsf{RI}} \quad \text{with} \quad \|\theta_k^{\mathsf{RI}}\|_F \le C_5 \,, \quad 1 \le k \le L \,.$$

Lemma (simplified)

For u > 0, with probability at least

$$1 - 8\exp\left(-\frac{du^2}{32s^2}\right),\,$$

it holds for all θ such that $\max_{1 \le k \le L} \|\theta_k\|_2 \le \frac{1}{64} \exp(-2s^2 - 4u)$ and all $k \in \{1, \dots, L\}$ that

$$\left\| \left(I + \frac{s}{\sqrt{Ld}} N_k + \frac{1}{L} \theta_k \right) \dots \left(I + \frac{s}{\sqrt{Ld}} N_1 + \frac{1}{L} \theta_1 \right) \right\|_2 \le 4 \exp\left(\frac{s^2}{2} + u\right) \right\|_2$$

and

$$\sigma_{\min}\left(\left(I + \frac{s}{\sqrt{Ld}}N_k + \frac{1}{L}\theta_k\right)\dots\left(I + \frac{s}{\sqrt{Ld}}N_1 + \frac{1}{L}\theta_1\right)\right) \ge \frac{1}{4}\exp\left(-\frac{2s^2}{d} - u\right).$$

Connection with sharpness

Theorem (M. and Chizat, 2024)

The minimizer \mathcal{W}^{RI} satisfies

$$W_k^{\mathsf{RI}} = I + \frac{s}{\sqrt{Ld}} N_k + \frac{1}{L} \theta_k^{\mathsf{RI}} \quad \text{with} \quad \|\theta_k^{\mathsf{RI}}\|_F \le C_5 \,, \quad 1 \le k \le L \,.$$

Corollary

If the data covariance matrix $\frac{1}{n}X^{\top}X$ is full rank, there exists C > 0 depending only on s such that the following bounds on the sharpness of the minimizer $\mathcal{W}^{\mathsf{RI}}$ hold:

$$1 \leq \frac{S(\mathcal{W}^{\mathsf{RI}})}{S_{\min}} \leq C \frac{\Lambda}{\lambda} \,.$$

Why does the sharpness increase during the early phase of training?



Damian, Nichani, Lee (2023)

Thank you!

Want to know more? arXiv:2405.13456





pierre.marion@epfl.ch https://pierremarion23.github.io > Mean squared error:

$$R^{L}(\mathcal{W}) = \frac{1}{n} \|y - XW_{1}^{\top} \dots W_{L}^{\top}p\|_{2}^{2}.$$

- **Assumption:** the covariance matrix $\frac{1}{n}X^{\top}X \in \mathbb{R}^{d \times d}$ is full-rank, with smallest and largest eigenvalues λ and Λ .
- The linear regression problem of y on X has a unique minimizer $\pi^* \in \mathbb{R}^d$.
- **Consequence:** all minimizers of $R^{L}(W)$ are equal in function space to $x \mapsto x^{\top} \pi^{\star}$.

Lower bounds on the sharpness of minimizers

Theorem (Mulayoff and Michaeli, 2020; M. and Chizat, 2024)

Let
$$S_{\min} = \inf_{\mathcal{W} \in \arg \min R^{L}(\mathcal{W})} S(\mathcal{W})$$
 and $a := (w^{\star}/||w^{\star}||)^{\top} \hat{\Sigma}(w^{\star}/||w^{\star}||)$. We have
 $S_{\min} \ge 2a ||w^{\star}||_{2}^{2-\frac{1}{L}} ||p||^{\frac{1}{L}} \sum_{k=1}^{L} \frac{1}{||W_{k}||_{F}},$

and

$$2\|w^{\star}\|_{2}^{2-\frac{2}{L}}\|p\|^{\frac{2}{L}}La \leq S_{\min} \leq 2\|w^{\star}\|_{2}^{2-\frac{2}{L}}\|p\|^{\frac{2}{L}}\sqrt{(2L-1)\Lambda^{2} + (L-1)^{2}a^{2}}$$

The sharpness of minimizers can be arbitrarily high: take any minimizer $W = (W_1, \ldots, W_L)$ and consider $W^C = (CW_1, W_2/C, W_3, \ldots, W_L)$. Then

$$S(\mathcal{W}^{C}) \geq \frac{2\lambda \|\pi^{\star}\|_{2}^{2-\frac{1}{L}}}{\|W_{2}/C\|_{F}} = \frac{2\lambda \|\pi^{\star}\|_{2}^{2-\frac{1}{L}}C}{\|W_{2}\|_{F}} \xrightarrow{C \to \infty} \infty.$$

How to lower-bound $|| W_L(t) \dots W_2(t) ||_2$?

$$\left\|\frac{\partial R^L}{\partial W_1}(t)\right\|_F^2 \ge 4\lambda \|W_L(t)\dots W_2(t)\|_2^2 (R^L(\mathcal{W}(t)) - R_{\min}).$$

> Two cases depending on the magnitude of $\sigma_1(t)$.

How to lower-bound $|| W_L(t) \dots W_2(t) ||_2$?

$$\left\|\frac{\partial R^L}{\partial W_1}(t)\right\|_F^2 \ge 4\lambda \|W_L(t)\dots W_2(t)\|_2^2 (R^L(\mathcal{W}(t)) - R_{\min}).$$

> If $\sigma_1(t)$ is "large":

Lemma (reminder)

The parameters following gradient flow satisfy for any $t \ge 0$ that

> for j, k ∈ {1,..., L},
$$|\sigma_k^2(t) - \sigma_j^2(t)| \le \varepsilon$$
.
> for k ∈ {1,..., L-1}, $\langle v_{k+1}(t), u_k(t) \rangle^2 \ge 1 - \frac{\varepsilon}{\sigma_{k+1}^2(t)}$.

How to lower-bound $||W_L(t) \dots W_2(t)||_2$?

$$\left\|\frac{\partial R^L}{\partial W_1}(t)\right\|_F^2 \ge 4\lambda \|W_L(t)\dots W_2(t)\|_2^2 (R^L(\mathcal{W}(t)) - R_{\min}).$$

> If $\sigma_1(t)$ is "small":

Assumption (reminder)

- Initialization such that $R^{L}(\mathcal{W}(0)) \leq \frac{1}{n} ||y||_{2}^{2}$ and $\nabla R^{L}(\mathcal{W}(0)) \neq 0$.
 - For $t \ge 1$, $\pi(\mathcal{W}(t))$ cannot be too close from 0.
 - Since $\sigma_1(t)$ is small, this implies that $||W_L(t) \dots W_2(t)||_2$ is large.

Deep linear networks with small-scale initialization

GF for deep linear networks for regression from a small-scale initialization:

- > converges to a global minimum.
- > the weights matrices are rank-one and aligned.
- > implicit regularization towards small norm and small sharpness.

Some prior work with a similar flavor

- Ji and Telgarsky (2018): aligned and rank-one layers for classification with linearly separable data.
- Saxe et al. (2014, 2019); Lampinen and Ganguli (2019); Gidel et al. (2019); Varre et al. (2023): implicit regularization towards low-rank structure in parameter space for two-layer neural networks.
- > Jacot et al. (2021): low-rank saddle-to-saddle dynamics for deep linear networks.

GF for deep linear networks for regression from a residual initialization:

- > converges when the initial risk is small enough.
- \blacktriangleright the change to weight matrices is of order $\mathcal{O}(1/L)$.
- > the final sharpness can be bounded.

Some prior work with a similar flavor

- Bartlett et al. (2018); Arora et al. (2019); Zou et al. (2020); Sander et al. (2022); Marion et al. (2024): convergence for identity or weight-tied initialization.
- Marion et al. (2022); Zhang et al. (2022): similar concentration bounds for product of random matrices.