Quadrature rules for splines of high smoothness on uniformly refined triangles

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Let $T := \langle p_1, p_2, p_3 \rangle$ be a non-degenerate triangle. The Hammer-Stroud quadrature rules are defined as (Hammer, Stroud MTAC 1956)

•
$$Q_{\text{HS},2}[f] := \frac{1}{3} |T| (f(t_{1,2}) + f(t_{2,2}) + f(t_{3,2}))$$

• $Q_{\text{HS},3}[f] := |T| \left(\frac{25}{48} \left(f(\mathbf{t}_{1,3}) + f(\mathbf{t}_{2,3}) + f(\mathbf{t}_{3,3}) \right) - \frac{27}{48} f(\mathbf{p}_c) \right)$

satisfy





- Is the Hammer-Stroud quadrature rule Q_{HS,2} still exact for the larger space S₁, where dim(S₁) > dim(P₂)?
- Is the Hammer-Stroud quadrature rule Q_{HS,3} still exact for the larger space S₂, where dim(S₂) > dim(P₃)?



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- Is the Hammer-Stroud quadrature rule Q_{HS,2} still exact for the larger space S₁, where dim(S₁) > dim(P₂)?
- Is the Hammer-Stroud quadrature rule Q_{HS,3} still exact for the larger space S₂, where dim(S₂) > dim(P₃)?

The answer is positive :





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Let T_{ℓ} be a split of a triangle T into ℓ sub-triangles. The spline space of global smoothness r and degree d is defined as:

$$\mathbb{S}_{d}^{r}\left(\mathcal{T}_{\ell}
ight):=\left\{s\in\mathcal{C}^{r}\left(\mathcal{T}
ight);\quad s_{\mid\bigtriangleup}\in\mathbb{P}_{d}\quadorall\,\vartriangle\in\mathcal{T}_{\ell}
ight\}$$

CT-3-split (Clough, Tocher 1965) $\#\mathbb{S}_3^1(T_3) = \#\mathbb{P}_3 + 2$



PS-6-split (Powell, Sabin 1977) $\#\mathbb{S}_2^1(T_6) = \#\mathbb{P}_2 + 3$



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 $\#\mathbb{S}_3^1(T_3) = \#\mathbb{P}_3 + 2$

 $\#\mathbb{S}_{2}^{1}(T_{6}) = \#\mathbb{P}_{2} + 3$

- $\mathbb{S}_3^1(T_3) = \mathbb{P}_3 \oplus \{D_1, D_2\}$
- $D_i \in C^1$, and $D_{i|\triangle} \in \mathbb{P}_3$
- D_{i|micro-edge} = 0, & ∫_T D_i = 0 Bartoň, Kosinka 2019

- $\mathbb{S}_{2}^{1}(T_{6}) = \mathbb{P}_{2} \oplus \{D_{1}, D_{2}, D_{3}\}$
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$\#\mathbb{S}_{3}^{1}(T_{3}) = \#\mathbb{P}_{3} + 2$

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- $\mathbb{S}_{2}^{1}(T_{6}) = \mathbb{P}_{2} \oplus \{D_{1}, D_{2}, D_{3}\}$
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This technique cannot be generalized to cases involving high degrees or multiple variables.





Let:

•
$$V_1, \ldots, V_{d+3} \in \mathbb{R}^2$$
 be a sequence of knots.
• $V = \{V_1, \ldots, V_{d+3}\} \subset \mathbb{R}^2$.
• $\Theta = \left\langle \widehat{V}_1, \ldots, \widehat{V}_{d+3} \right\rangle$ be a simplex in \mathbb{R}^{d+2} .
• $\Pi : \mathbb{R}^{d+2} \longrightarrow \mathbb{R}^2$ be the projection of Θ into \mathbb{R}^2 satisfies
 $\Pi \left(\widehat{V}_i \right) = V_i, \qquad i = 1, \ldots, d+3.$

The unit integral bivariate simplex S_V can be defined geometrically as follows

$$\mathsf{S}_{\mathsf{V}}(\mathsf{x}) := rac{\mathsf{vol}_{2}\left(\Theta \cap \Pi^{-1}(\mathsf{x})
ight)}{\mathsf{vol}_{d+2}\left(\Theta
ight)}$$

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The simplex S_V meets some useful properties:

- S_V is a non-negative spline of degree $\leq d$ and support $\langle V \rangle$.
- For d = 0 we have

$$S_{\mathsf{V}} = \begin{cases} \frac{1}{\mathsf{Area}(\langle \mathsf{V} \rangle)}, & \text{if } \mathsf{x} \in \langle \mathsf{V} \rangle^{\circ}\,, \\ 0, & \text{if } \mathsf{x} \notin \langle \mathsf{V} \rangle^{\circ}\,, \end{cases}$$

• Local smoothness: The simplex S_V is $C^{d+1-\mu}$ continuous across a knot line, where μ is the number of knots including multiplicity on that knot line.





The simplex S_V meets some useful properties:

- S_V is a non-negative bivariate piecewise polynomial of total degree $\leq d$ and support $\langle V \rangle$.
- For d = 0 we have

$$S_{\mathsf{V}} = \begin{cases} \frac{1}{\mathsf{Area}(\langle \mathsf{V} \rangle)}, & \text{if } \mathsf{x} \in \langle \mathsf{V} \rangle^{\circ} \,, \\ 0, & \text{if } \mathsf{x} \notin \langle \mathsf{V} \rangle^{\circ} \,, \end{cases}$$

where $\langle V\rangle^\circ$ marks the open convex hull of the knots sequence V.

- Local smoothness: The simplex S_V is $C^{d+1-\mu}$ continuous across a knot line, where μ is the number of knots including multiplicity on that knot line.
- A normalized simplex spline is defined by:

$$N_{V} := \frac{\operatorname{Area}(V)}{\binom{d+2}{2}} S_{V}$$

Simplex spline: Knot insertion

For any $p \in \mathbb{R}^2$, and any $\beta_1, \ldots, \beta_{d+3} \in \mathbb{R}$ such that $p = \sum_{i=1}^{d+3} \beta_i p_i$, $\sum_{i=1}^{d+3} \beta_i = 1$, it holds

$$N_{[\mathbf{p}_1,\ldots,\mathbf{p}_{d+3}]} = \sum_{i=1}^{d+3} \beta_i N_{[\mathbf{p}_1,\ldots,\mathbf{p}_{d+3},\mathbf{p}]\setminus\mathbf{p}_i}.$$

Examples:

• 1D:



Simplex spline: Knot insertion

For any $p \in \mathbb{R}^2$, and any $\beta_1, \ldots, \beta_{d+3} \in \mathbb{R}$ such that $p = \sum_{i=1}^{d+3} \beta_i p_i$, $\sum_{i=1}^{d+3} \beta_i = 1$, it holds

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Examples:

• 2D: $p = \alpha_1 p_1 + \alpha_2 p_2 + \alpha_3 p_3$,

 $N_{[p_1[4],p_2[2],p_3[3]]} = \alpha_1 N_{[p_1[3],p_2[2],p_3[3],p]} + \alpha_2 N_{[p_1[4],p_2,p_3[3],p]} + \alpha_3 N_{[p_1[4],p_2[2],p_3[2],p]}$



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Simplex spline: Notation

Let $T = \langle p_1, p_2, p_3 \rangle$ represent a non-degenerate triangle, where $p_c = \frac{p_1 + p_2 + p_3}{3}$ denotes the barycenter of T, and $p_{i,j} = \frac{p_i + p_j}{2}$ represents the midpoint of the edge $\langle p_i, p_j \rangle$. The following notation is considered:

• CT-3-split:

$$= N_{[p_1[i], p_2[j], p_3[k], p_c[\ell] }$$

• PS-6-split:



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Symmetric quadrature rules

Here we are interested in integrals of the form

$$\int_{\mathcal{T}} f(x) \mathrm{d}x,$$

where f is a given function on the triangle T. Let $n \in \mathbb{N}$, n > 0 and a function space S be given. We denote by

$$\mathcal{Q}_{n,\mathbb{S}}(f) := \operatorname{Area}(T) \sum_{i=1}^{n} \omega_i f(\mathsf{t}_i)$$

an *n*-node QR that is exact for any function in the space S, i.e.,

$$\mathcal{Q}_{n,\mathbb{S}}(f) = \int_{\mathcal{T}} f(x) \mathrm{d}x \;\; ext{for all} \; f \in \mathbb{S}.$$

The points $t_i \in T$, are the nodes of $Q_{n,S}$ and ω_i are the corresponding GAT weights.

A QR $Q_{n,\mathbb{S}}$ is said to be symmetric if it maintains its properties under rotation around the barycenter and reflection with respect to the medians of the triangle. Namely, if t $(\alpha_1, \alpha_2, \alpha_3)$ is a node of $Q_{n,\mathbb{S}}$ with the corresponding weight ω , then for every permutation Π of $(\alpha_1, \alpha_2, \alpha_3)$, the node t_{Π} (Π ($\alpha_1, \alpha_2, \alpha_3$)) is also a node of $Q_{n,\mathbb{S}}$ with the same weight ω .

- type-0-orbit t (1/3, 1/3, 1/3)
- type-1-orbit t $(1 2\alpha, \alpha, \alpha)$
- type-2-orbit t ($\alpha, \beta, \gamma = 1 \alpha \beta$) ($\alpha \neq \beta \neq \gamma$)



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Symmetric quadrature rules

• type-0-orbit t (1/3, 1/3, 1/3)• type-1-orbit t $(1 - 2\alpha, \alpha, \alpha)$



• type-2-orbit t ($\alpha, \beta, \gamma = 1 - \alpha - \beta$) ($\alpha \neq \beta \neq \gamma$)





Symmetric quadrature rules

The notation $\mathcal{Q}_{[n_0,n_1,n_2],\mathbb{S}}$ represents the QR that uses:

- n₀ type-0 orbits,
- n₁ type-1 orbits,
- n₂ type-2 orbits.

The total number of nodes in this QR is given by





For any $0 \le \rho < d$, we have

$$\dim \mathbb{S}^{\rho}_{d}(T_3) = \binom{\rho+2}{2} + 3\binom{d-\rho+1}{2} + \sum_{j=1}^{d-\rho} \max\{\rho+1-2j,0\}.$$

It holds:

$$\#\mathbb{S}_{3r}^{2r-1}(T_3) = \#\mathbb{P}_{3r} + 2.$$

Examples:

$$\mathbb{S}_{3}^{1}(T_{3}) = \#\mathbb{P}_{3} + 2, \quad \mathbb{S}_{6}^{3}(T_{3}) = \#\mathbb{P}_{6} + 2, \quad \mathbb{S}_{9}^{5}(T_{3}) = \#\mathbb{P}_{9} + 2.$$



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$\#\mathbb{S}_{3}^{1}(T_{3}) = \#\mathbb{P}_{3} + 2$



S. Eddargani et al

Optimal Quadrature rules

$\#\mathbb{S}_3^1(T_3) = \#\mathbb{P}_3 + 2$

•
$$\mathbb{P}_3 = \operatorname{span}\left\{ \underbrace{k+1}_{i+1-i+1}, \quad i+j+k=3 \right\}$$



$\#\mathbb{S}_{3}^{1}(T_{3}) = \#\mathbb{P}_{3} + 2$

•
$$\mathbb{P}_3 = \operatorname{span}\left\{ \underbrace{k+1}_{i+1-i+1}, \quad i+j+k=3 \right\}$$

• Knot insertion:

$$2 = \frac{1}{3} \begin{pmatrix} 2 \\ 1 \\ 1 \\ 2 \end{pmatrix} + \begin{pmatrix} 2 \\ 2 \\ 1 \\ 2 \end{pmatrix} + \begin{pmatrix} 1 \\ 2 \\ 1 \\ 2 \end{pmatrix}$$



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$\#\mathbb{S}_{3}^{1}(T_{3}) = \#\mathbb{P}_{3} + 2$

•
$$\mathbb{P}_3 = \operatorname{span}\left\{ \underbrace{k+1}_{i+1-i+1}, \quad i+j+k=3 \right\}$$

Knot insertion:

$$2 = \frac{1}{3} \left(2 + 2 + 1 \right) \left(1 - 2 + 2 + 1 \right)$$



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Theorem

Any quadrature rule $\mathcal{Q}_{[n_0,n_1,n_2],\mathbb{P}_3}$ is exact on the spline space $\mathbb{S}^1_3(T_3)$.



$$\#\mathbb{S}_{3r}^{2r-1}(T_3) = \#\mathbb{P}_{3r} + 2$$

$$\mathbb{S}_{3r}^{2r-1}(T_3) = \operatorname{span}\left\{ \underbrace{k+1}_{r+1-i+1}, \quad i+j+k = 3r \right\} \setminus \underbrace{r+1}_{r+1-r+1} \bigcup \left\{ \underbrace{r+1}_{r+1-i+1}, \\ \underbrace{r+1}_{r+1-r+1}, \\ \underbrace{r+1}_{r+1-r+1} \right\}$$

Theorem

Any quadrature rule $\mathcal{Q}_{[n_0,n_1,n_2],\mathbb{P}_{3r}}$ is exact on the spline space $\mathbb{S}_{3r}^{2r-1}(T_3)$.



For any $0 \le \rho < d$, we have

$$\dim \mathbb{S}^{\rho}_{d}(T_{6}) = \binom{\rho+2}{2} + 6\binom{d-\rho+1}{2} + \sum_{j=1}^{d-\rho} \max\{\rho+1-2j,0\}.$$

It holds:

$$\#\mathbb{S}_{2r}^{2r-1}(T_6) = \#\mathbb{P}_{2r} + 3.$$

Examples:

$$\mathbb{S}_{2}^{1}(T_{6}) = \#\mathbb{P}_{2} + 3, \quad \mathbb{S}_{4}^{3}(T_{6}) = \#\mathbb{P}_{4} + 3, \quad \mathbb{S}_{6}^{5}(T_{6}) = \#\mathbb{P}_{6} + 3.$$



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$\#\mathbb{S}_{2}^{1}(T_{6}) = \#\mathbb{P}_{2} + 3$

•
$$\mathbb{P}_2 = \operatorname{span} \left\{ \underbrace{i+j+1}_{i+1}, \quad i+j+k=2 \right\}$$

Knot insertion:



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$\#\mathbb{S}_{2}^{1}(T_{6}) = \#\mathbb{P}_{2} + 3$





S. Eddargani et al

Optimal Quadrature rules

SIGMA 2024 23 / 29

Theorem

Any quadrature rule $\mathcal{Q}_{[n_0,n_1,n_2],\mathbb{P}_2}$ is exact on the spline space $\mathbb{S}^1_2(T_6)$.



PS-6-split: Simplex spline basis for $\mathbb{S}_{2r}^{2r-1}(T_6)$

$\#\mathbb{S}_{2r}^{2r-1}(T_6) = \#\mathbb{P}_{2r} + 3$



Splines on uniformly refined tetrahedra

Could we apply similar techniques to trivariate splines?



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S. Eddargani et al

Optimal Quadrature rules

SIGMA 2024 26 / 29

Symmetric quadrature rules in \mathbb{R}^3

If $t(\alpha_1, \alpha_2, \alpha_3, \alpha_4)$ is a node of $\mathcal{Q}_{n,\mathbb{S}}$ with the corresponding weight ω , then for every permutation Π of $(\alpha_1, \alpha_2, \alpha_3, \alpha_4)$, the node $t_{\Pi}(\Pi(\alpha_1, \alpha_2, \alpha_3, \alpha_4))$ is also a node of $\mathcal{Q}_{n,\mathbb{S}}$ with the same weight ω .

- type-0-orbit t (1/4, 1/4, 1/4, 1/4)
- type-1-orbit t $(1 3\alpha, \alpha, \alpha, \alpha)$
- type-2-orbit t (1 2 α β , β , α , α)
- type-3-orbit t ($\alpha, \beta, \gamma, \delta = 1 \alpha \beta \gamma$) ($\alpha \neq \beta \neq \gamma \neq \delta$)



Let T_{ℓ} be a split of a tetrahedra $T = \langle p_1, p_2, p_3, p_4 \rangle$ into ℓ sub-tetrahedra. The spline space of trivariate global smoothness r and degree d is defined as:

$$\mathbb{S}_{d}^{r}\left(\mathcal{T}_{\ell}
ight):=\left\{ s\in\mathcal{C}^{r}\left(\mathcal{T}
ight);\quad s_{\mid\bigtriangleup}\in\mathbb{P}_{d}\quadorall\,\vartriangle\in\mathcal{T}_{\ell}
ight\}$$



FW-12-split (Farin Worsey 1987) $\#\mathbb{S}_{3}^{1}(T_{12}) = \#\mathbb{P}_{3} + 8$

WP-24-split (Worsey-Piper 1988) $\#\mathbb{S}_{2}^{1}(T_{24}) = \#\mathbb{P}_{2} + 6$



AL-4-
$$(\mathbb{S}_{4}^{1}(T_{4}))$$
, FW-12- $(\mathbb{S}_{3}^{1}(T_{12}))$ & WP-24-split $(\mathbb{S}_{2}^{1}(T_{24}))$

Theorem

- Any quadrature rule $\mathcal{Q}_{[n_0,n_1,n_2,n_3],\mathbb{P}_4}$ is exact on the spline space $\mathbb{S}_4^1(T_4)$ (Alfeld).
- Any quadrature rule $Q_{[n_0,n_1,n_2,n_3],\mathbb{P}_3}$ is exact on the spline space $\mathbb{S}_3^1(T_{12})$ (Farin-Worsey).
- Any quadrature rule $Q_{[n_0,n_1,n_2,n_3],\mathbb{P}_2}$ is exact on the spline space $\mathbb{S}_2^1(T_{24})$ (Worsey-Piper).



AL-4-
$$(\mathbb{S}_{4}^{1}(T_{4}))$$
, FW-12- $(\mathbb{S}_{3}^{1}(T_{12}))$ & WP-24-split $(\mathbb{S}_{2}^{1}(T_{24}))$

Theorem

- Any quadrature rule $\mathcal{Q}_{[n_0,n_1,n_2,n_3],\mathbb{P}_4}$ is exact on the spline space $\mathbb{S}_4^1(T_4)$ (Alfeld).
- Any quadrature rule $Q_{[n_0,n_1,n_2,n_3],\mathbb{P}_3}$ is exact on the spline space $\mathbb{S}_3^1(T_{12})$ (Farin-Worsey).
- Any quadrature rule $Q_{[n_0,n_1,n_2,n_3],\mathbb{P}_2}$ is exact on the spline space $\mathbb{S}_2^1(T_{24})$ (Worsey-Piper).

Thank you

